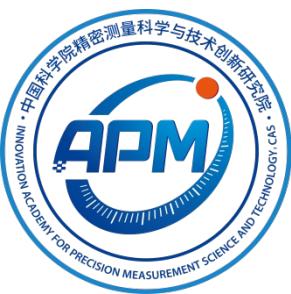


FOMO2024



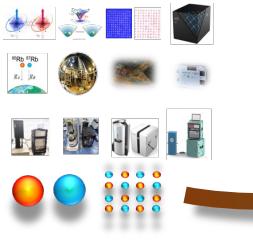
Atom Interferometry in Space

Mingsheng Zhan (詹明生)



中国科学院精密测量科学与技术创新研究院
Innovation Academy for Precision Measurement Science and Technology, CAS

2024.9.10 Crete

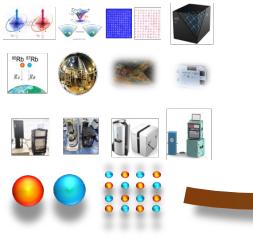


OUTLINE

- Why AI in space
- Path of AI to space
- CSS-AI: payload
- CSS-AI: experiments

AI: Atom Interferometer

CSS: China Space Station



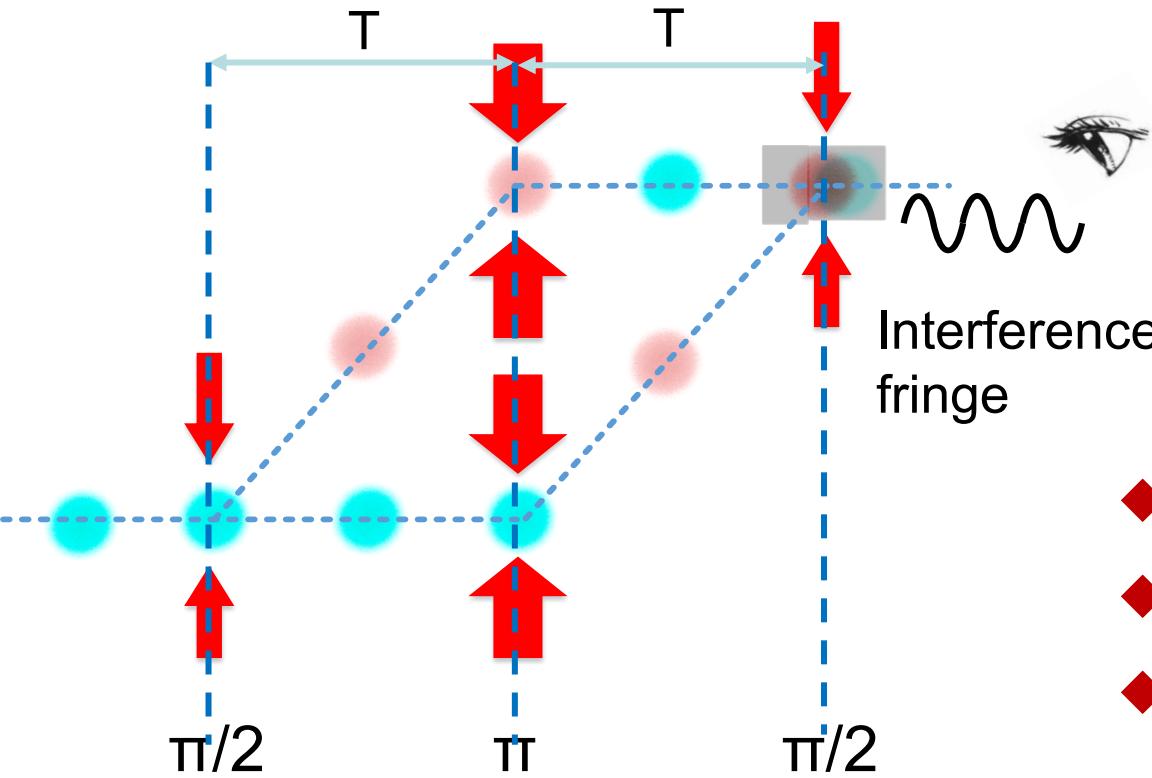
OUTLINE

- Why AI in space
- Path of AI to space
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- CSS-AI: experiments

Atom interferometer and its application

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Atom interferometer (AI)



The phase of the fringe

$$\phi = \vec{k}_{eff} (\vec{a} + \vec{\Omega} \times \vec{v}) T^2$$

Applications

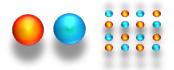
Applied Physics

- ◆ Gravity survey
- ◆ Navigation
- ◆ Resource exploration

Fundamental physics

- ◆ EP test
- ◆ Fine structure constant
- ◆ Gravitational constant
- ◆ Frame dragging effect
- ◆ Gravitational wave
- ◆ Dark matter

Roadmap of EP test with AI@APM



Equivalence Principle (EP) Test
to check the Eötvös-parameter

$$\eta \equiv \frac{g_a - g_b}{(g_a + g_b)/2} = \frac{(g_a - \textcolor{red}{a}_c) - (g_b - \textcolor{red}{a}_c)}{(g_a + g_b)/2} \stackrel{?}{=} 0 \quad \text{Sensitivity}$$



^{85}Rb ^{87}Rb

g_a g_b



T

Free evolution time

0.2 s

→ 1.3 s

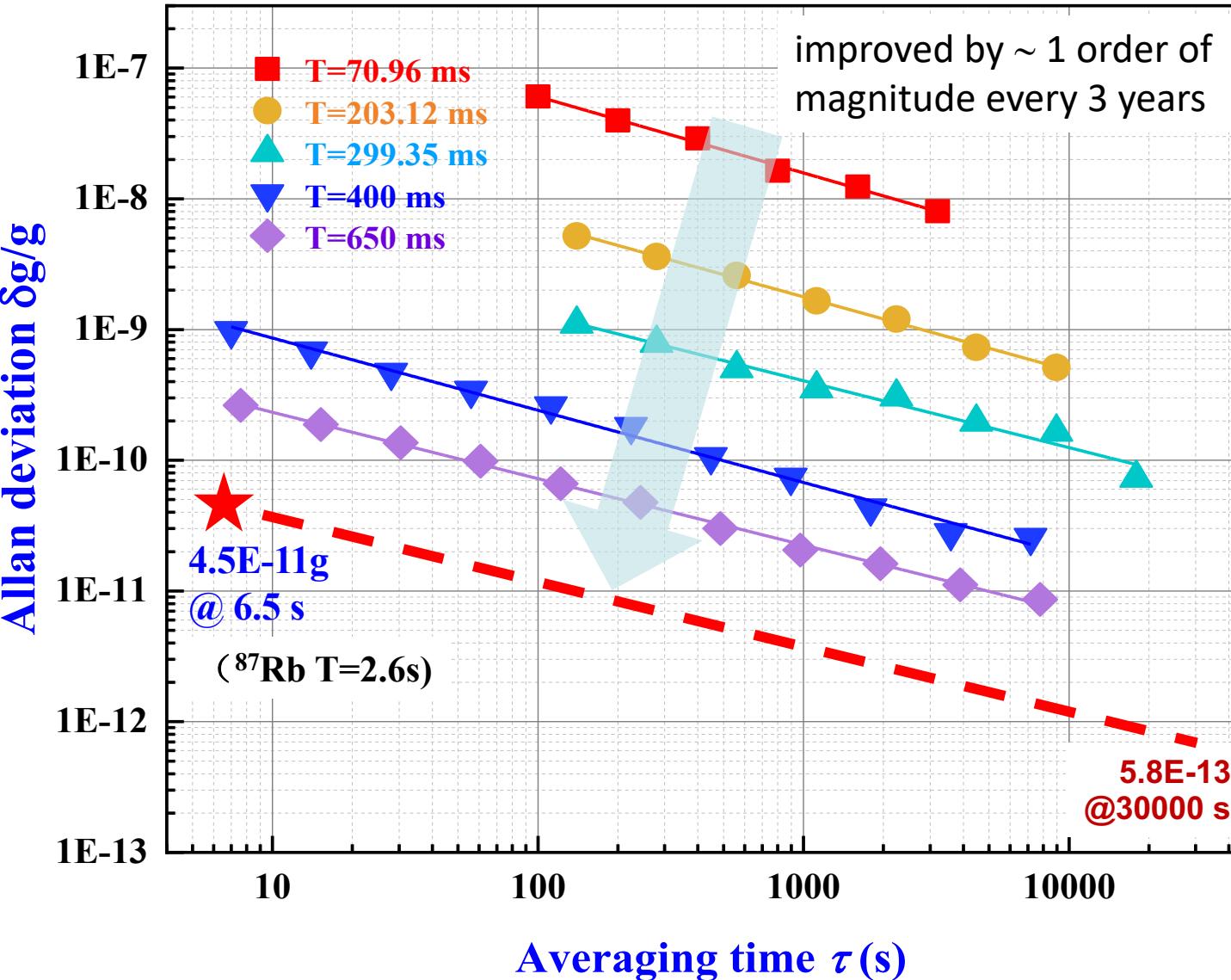
10-m Tower

→ 7 s

100-m Tower

→ (2 ~ 100) s Space Satellite

Sensitivity Improvement of the Wuhan 10-m AI (2015-)



2015

4WDR method

L. Zhou, S.T. Long et al. *Phys. Rev. Lett.* **115**, 013004 (2015)

8E-9

2018

Coriolis effect compensation

W. T. Duan, C. He et al. *Chin. Phys. B* **29**, 070305(2020)

5.1E-10

2020

AC Stark shift Optimization

L. Zhou, C. He et al. *Phys. Rev. A* **104**, 022822 (2021)

7.3E-11

2022

Shear phase readout

L. Zhou, S. T. Yan et al. *Frot. Phys.* **10**, (2022)

S. T. Yan et al. *Phys. Rev. A* **108**, 063313 (2023)

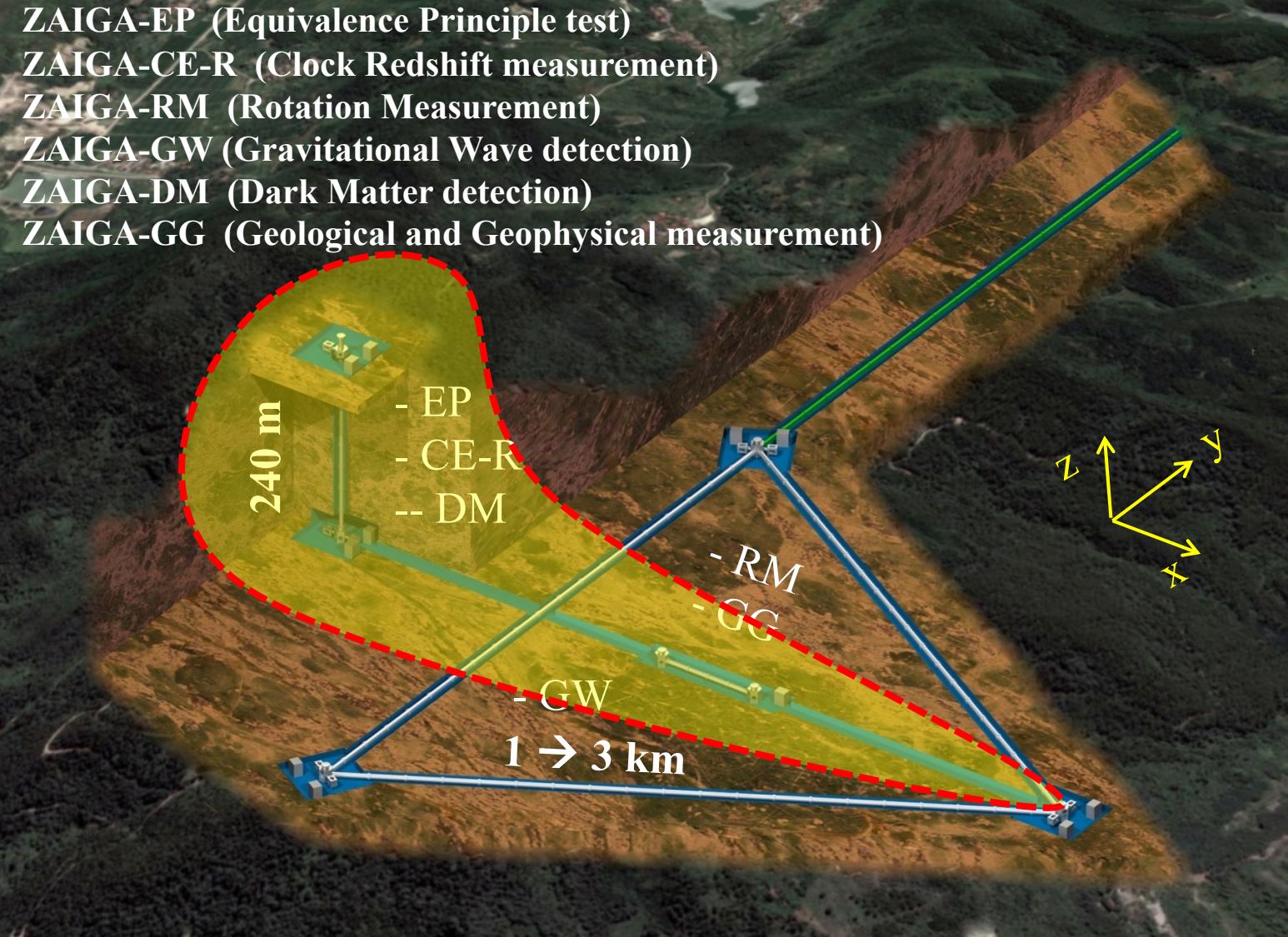
2.5E-11

2023

Gravity gradient compensation

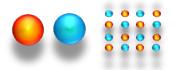
8.6E-12

ZAIGA: Zhaoshan long-baseline Atom Interferometer Gravitation Antenna



to test gravity theory by atomic interferometer, atomic optical clock and atomic gyroscope

Research Roadmap of ZAIGA



Building abilities

Item	Goal
AI baseline (Falling time)	$240\text{ m } (\text{T} \geq 6\text{ s})$
Atom species for AI	^{85}Rb ^{87}Rb ^{87}Sr ^{88}Sr
Gravity measurement	$1 \times 10^{-12}\text{ g}$
Rotation measurement	$8 \times 10^{-12}\text{ rad/s}$
Stability of Sr/Yb clock	2×10^{-18}
Local gravity monitoring	$1\text{ }\mu\text{Gal}$



Phase I
2022 - 2027

240 m Vertical AI
20 m Gyros
10 m Dual Rb/Sr AI
2E-18 Optical Clocks

Scientific Tests

Item	Goal
WEP test	$\eta \sim 10^{-13}$
Redshift test	$\alpha \sim 10^{-5}$
Lense-Thirring effect	$\sim 10^{-14}\text{ rad/s}$
Dark matter probe	$d \sim 10^{-4} @ 1\text{ Hz}$
GW detection	$s \sim 10^{-19} @ 1\text{ Hz}$

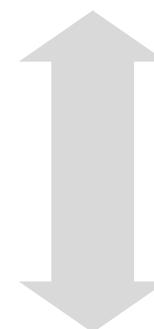


Phase II:
2027 - 2035

240 m Vertical AI array
 Δ 1000 m Horizontal AI array

DM & GW

Item	Goal
Dark matter probe	$d \sim 10^{-6} @ 1\text{ Hz}$
GW detection	$s \sim 10^{-21} @ 1\text{ Hz}$



Phase III
2035 -

ZAIGA

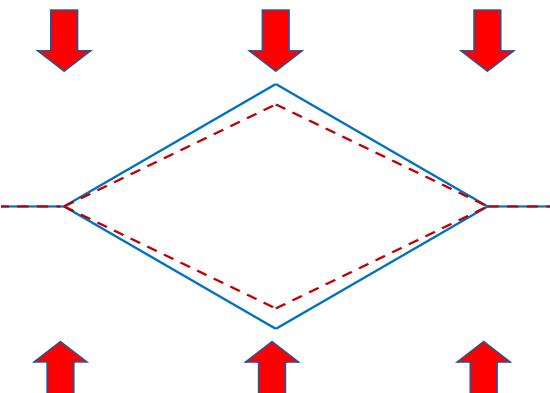
$\geq 3000\text{ m}$ Horizontal AI

AI in space

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Advantages in space

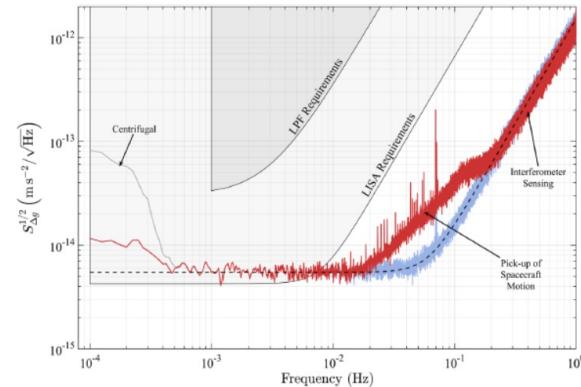
Long Interference time



1.2 m Separation of the wave packet for T=50 s

Mainly limited by the temperature of the atom cloud

Extremely quiet vibration environment



Residual acceleration
 $10^{-11}\sim 10^{-15} \text{ m/s}^2$
(Drag free control)

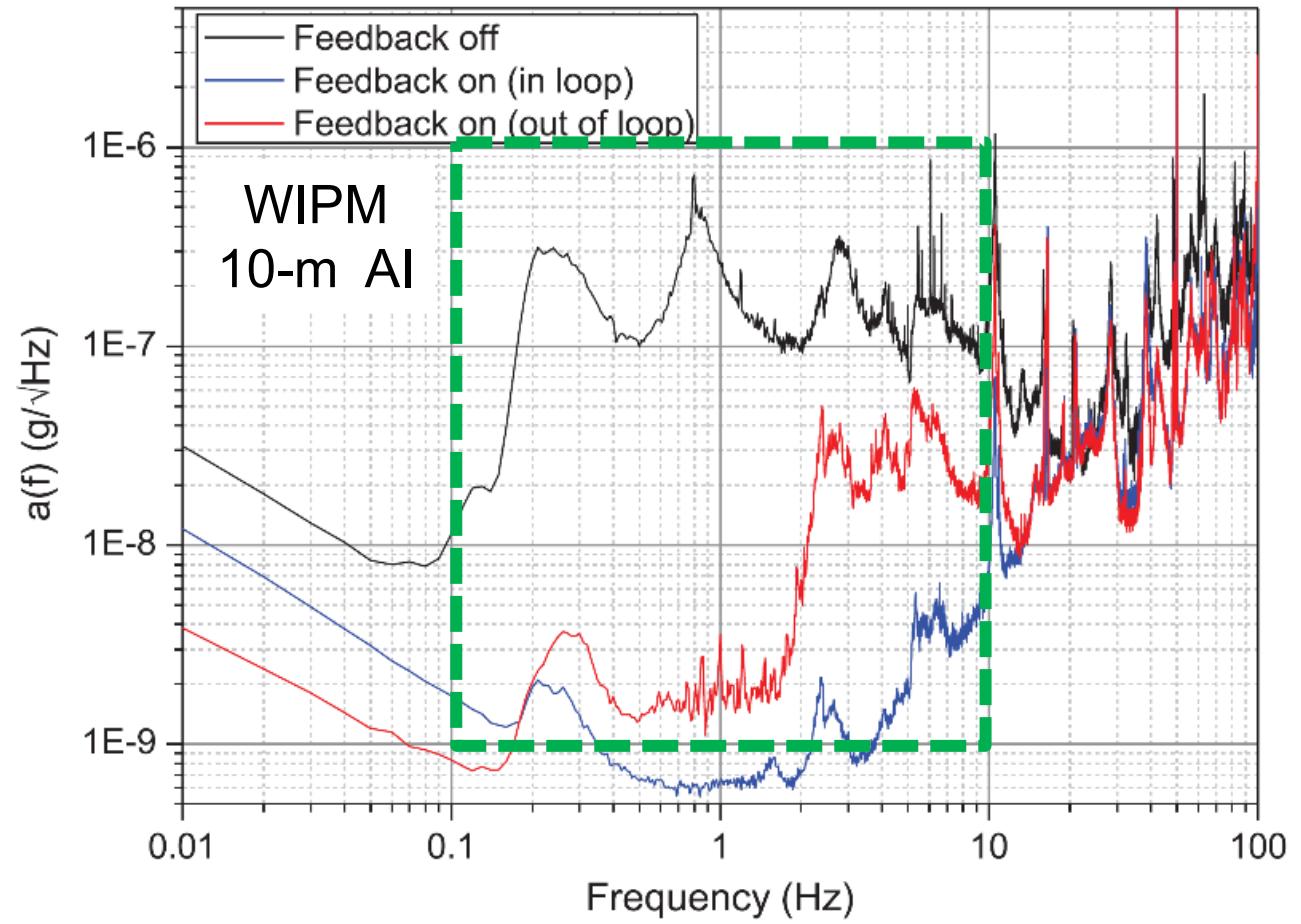
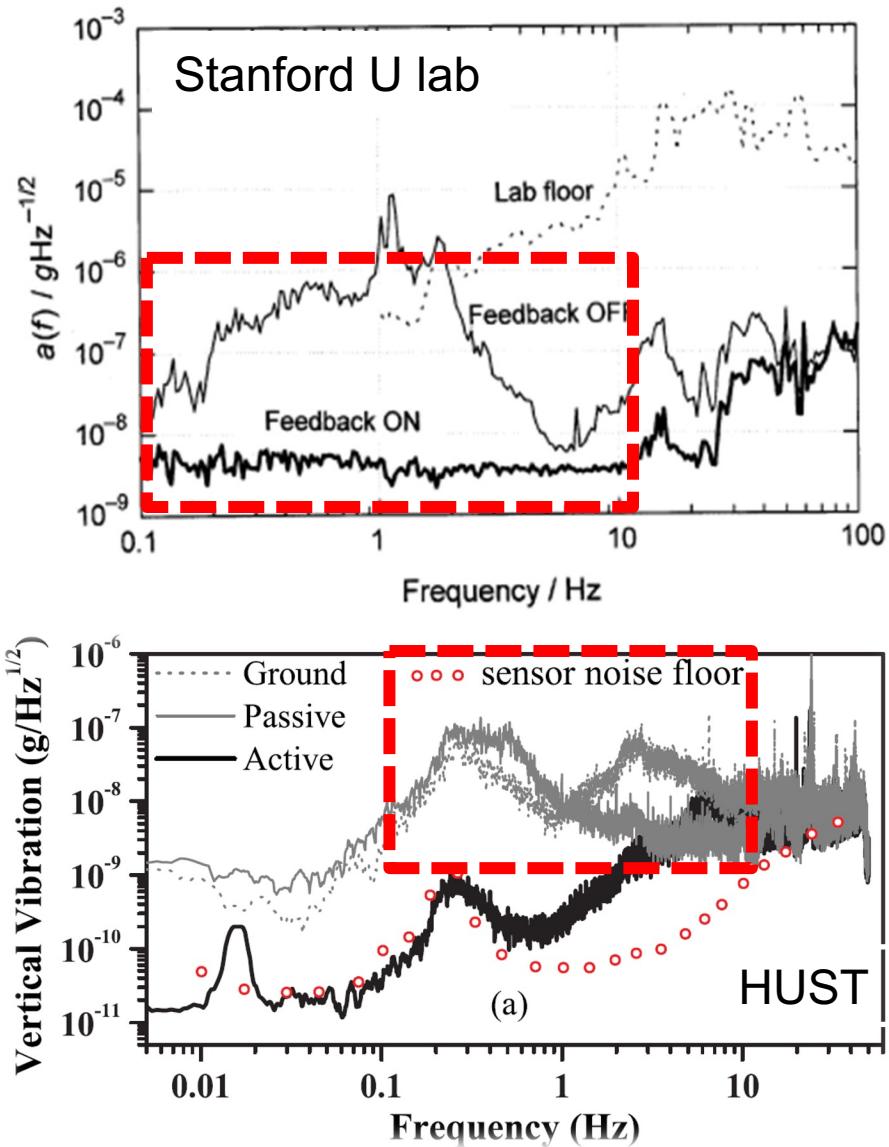
Much better than ground

Challenges

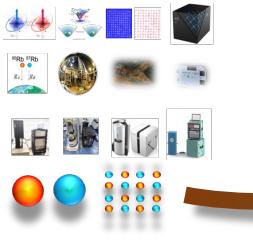
- ◆ Requirement for the spacecraft
(Residual acceleration, structural stability, Residual magnetization control)
- ◆ Vibration during rocket launch
- ◆ Vacuum environment
- ◆ Reliability, Long life time
- ◆ High-energy particle radiation in space

Vibrational noises on the Ground

ZMS - AMP



B. Tang et al., Rev. Sci. Instrum. 85, 093109 (2014)



OUTLINE

- Why AI in space
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- CSS-AI: payload
- CSS-AI: experiments

Space AI proposals

ZMS - AMP

El-Neaj et al. EPJ Quantum Technology (2020) 7:6

<https://doi.org/10.1140/epjqt/s40507-020-0080-0>



RESEARCH

Open Access

AEDGE: Atomic Experiment for Dark Matter and Gravity Exploration in Space



Alonso et al. EPJ Quantum Technology (2022) 9:30

<https://doi.org/10.1140/epjqt/s40507-022-00147-w>

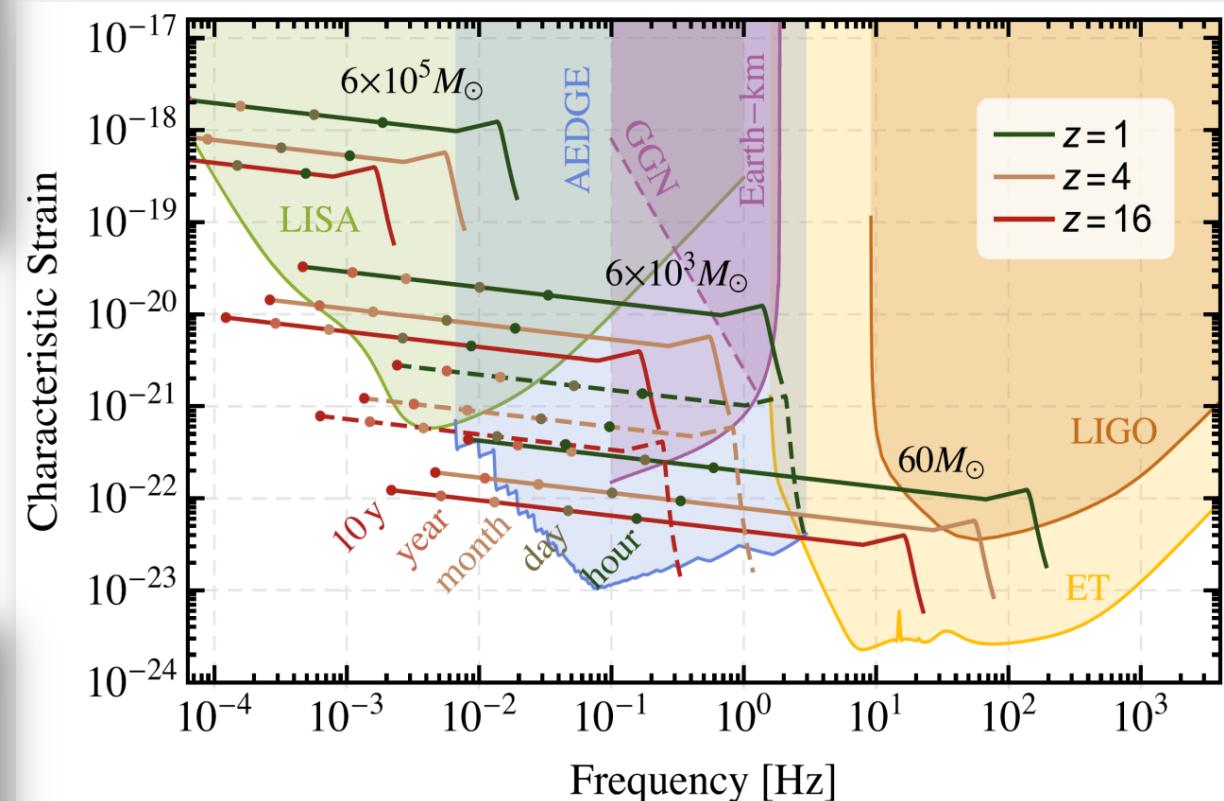


REVIEW

Open Access

Cold atoms in space: community workshop summary and proposed road-map

EPJ Quantum Technology
a SpringerOpen Journal



Space AI proposals

ZMS - AMP

Technology roadmap for cold-atoms based quantum inertial sensor in space

Cite as: AVS Quantum Sci. 5, 019201 (2023); doi: [10.1116/5.0098119](https://doi.org/10.1116/5.0098119)

Submitted: 5 May 2022 · Accepted: 22 November 2022 ·

Published Online: 20 March 2023



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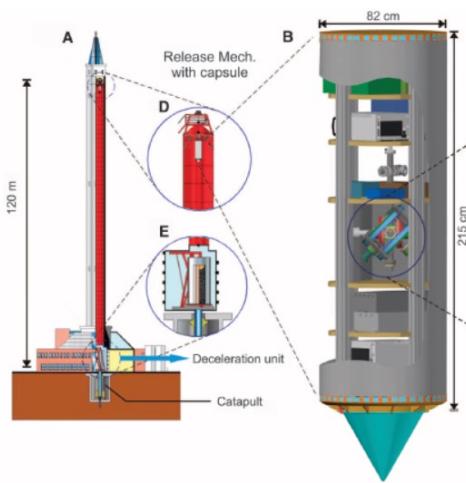


[CrossMark](#)

Sven Abend,¹ Baptiste Allard,² Aidan S. Arnold,³ Ticijana Ban,⁴ Liam Barry,⁵ Baptiste Battelier,⁶ Ahmad Bawamia,⁷ Quentin Beaufils,⁸ Simon Bernon,⁶ Andrea Bertoldi,⁶ Alexis Bonnin,⁹ Philippe Bouyer,^{6,10,11,12,13} Alexandre Bresson,⁹ Oliver S. Burrow,³ Benjamin Canuel,⁶ Bruno Desruelle,¹³ Giannis Drougakis,¹⁴ René Forsberg,¹⁵ Naceur Gaaloul,¹ Alexandre Gauguet,² Matthias Gersemann,¹ Paul F. Griffin,³ Hendrik Heine,¹ Victoria A. Henderson,¹⁶ Waldemar Herr,^{1,17} Simon Kanthak,¹⁸ Markus Krutzik,^{7,18} Maike D. Lachmann,¹ Roland Lammegger,¹⁹ Werner Magnes,²⁰ Gaetano Miletí,²¹ Morgan W. Mitchell,²² Sergio Mottini,²³ Dimitris Papazoglou,¹⁴ Franck Pereira dos Santos,²⁴ Achim Peters,¹⁶ Ernst Rasel,¹ Erling Riis,³ Christian Schubert,^{1,17} Stephan Tobias Seidel,²⁵ Guglielmo M. Tino,²⁶ Mathias Van Den Bossche,²³ Wolf von Klitzing,¹⁴ Andreas Wicht,⁷ Marcin Witkowski,²⁷ Nassim Zahzam,⁹ and Michał Zawada²⁷

AI taking off from the ground

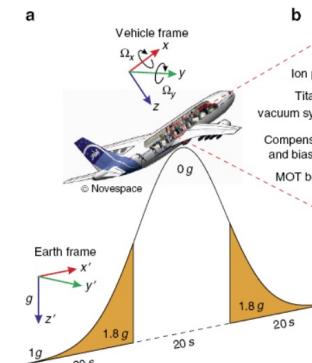
Dropping tower



- Bose-Einstein Condensation in Microgravity(2010)
- Interferometry with Bose-Einstein Condensates in Microgravity(2013)

T. van Zoest, et al. Science 328, 1540,2010
H. Muntinga, et al. PRL 110, 093602,2013

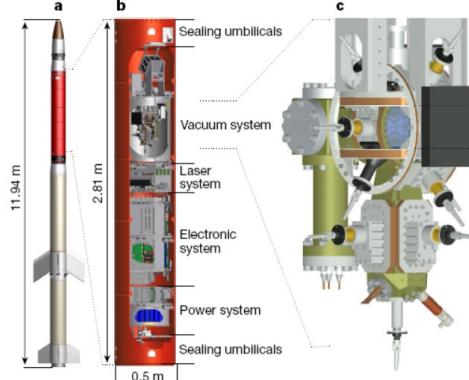
Parabolic flying plane



- Detecting inertial effects with airborne matter-wave interferometry(2011)
- Dual matter-wave inertial sensors in weightlessness(2016)

R. Geiger, et al. NATURE COMMUNICATIONS, 2:474, 2011
Brynle Barrett, et al. NATURE COMMUNICATIONS, 7:13786, 2016

Sounding rocket



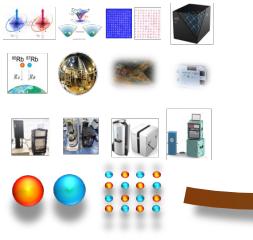
- Space-borne Bose–Einstein condensation for precision interferometry (2018)
- Ultracold atom interferometry in space(2021)

Dennis Becker, et al. NATURE, 562, 18, 2018

Maike D. Lachmann, et al. NATURE COMMUNICATIONS, 12:1317,2021

ISS-AI vs CSS-AI

	ISS-CAL	CSS-AI
Science objectives	<ul style="list-style-type: none">● Ultra cold atom preparation● Quantum gases research● Atom interferometry● EP test	<ul style="list-style-type: none">● Atom interferometry● Rotation measurement● Gravity measurement● EP test
Atom species	^{87}Rb , ^{41}K and ^{39}K	^{85}Rb and ^{87}Rb
Atom cooling scheme	Atom chip	2D+3D laser cooling
Cold atom cloud parameters	Number 10^4 Temperature $<1\text{ nK}$	Number $>5\times 10^8$ Temperature $2\text{ }\mu\text{K}$
Interference scheme	Bragg transition	Double diffraction Raman transition
Achieved interference time	150 ms	200 ms
payload parameters	Size about $90\text{ cm}\times 55\text{ cm}\times 50\text{cm}$ Power up to 1000 W	Size $46\text{ cm}\times 33\text{ cm}\times 26\text{ cm}$ Power 70 W

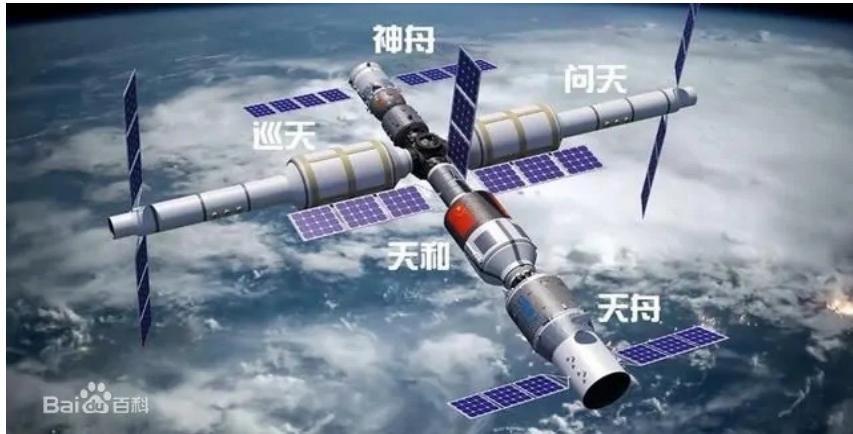


OUTLINE

- Why AI in space
- Path of AI to space
- **CSS-AI: payload**
- **CSS-AI: experiments**

AI in the China Space Station

The China space station



High Microgravity Level
Research Rack (HMLR)

The China Space Station
Atom Interferometer (CSS-AI)

Scientific objectives

Carrying out in-orbit experiments for AI measurements and EP test.

Target accuracy

Interference time: 0.1~1 s

Test mass: ^{85}Rb and ^{87}Rb

EP test precision: $\sim 10^{-10}$

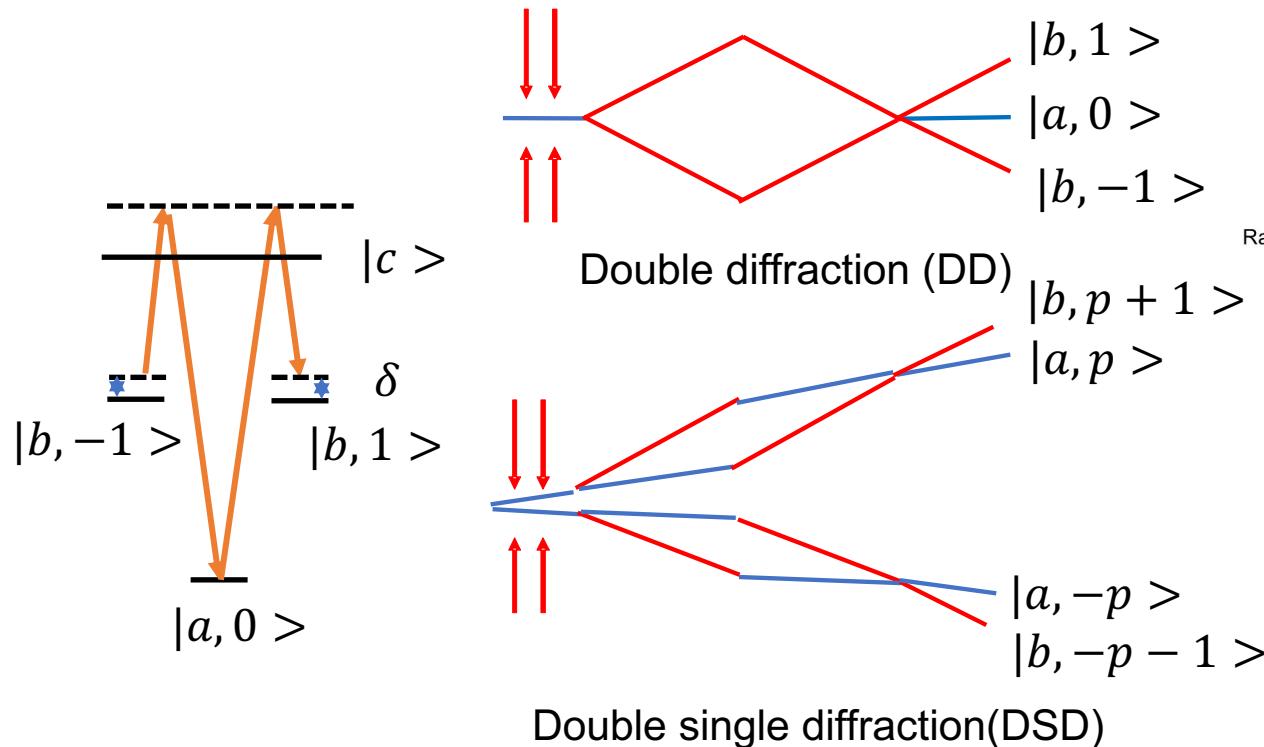


Resources provided by HMLR

- Micro gravity: 10^{-7}g
- size: $33\text{ cm} \times 46\text{ cm} \times 26\text{ cm}$
- power: $\sim 70\text{ W}$
- Installing: levitation, no heat dissipation channel

The interference scheme

Problem1: lacking initial velocity of the atom cloud
Energy levels of the Raman transition are degenerate



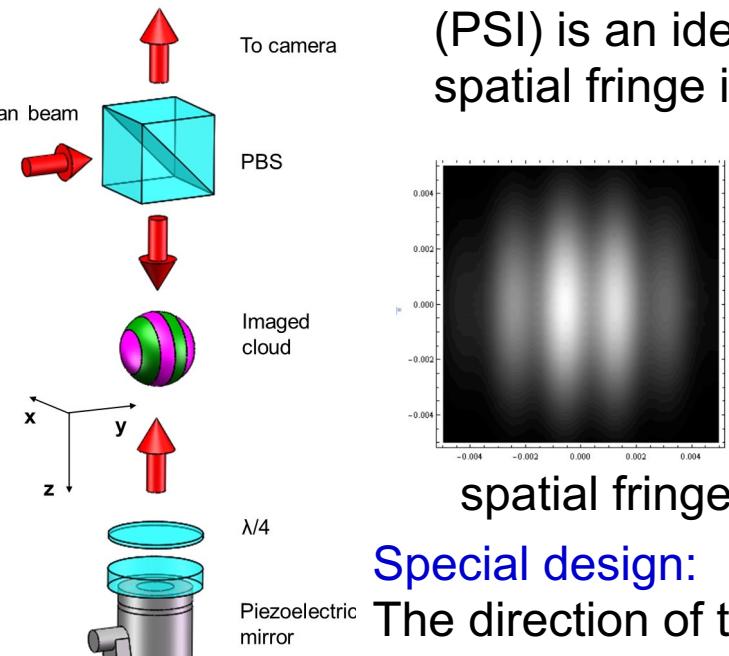
Two interference schemes can be transformed by changing the frequency of the Raman laser.

N. Malossi, et al. PRA 81, 013617 (2010)

Brynle Barrett, et al. NATURE COMMUNICATIONS, 7:13786, 2016

Problem2: Both DD and DSD are immune to the phase of the Raman laser in space
One can not obtain the interference fringe by scanning the phase of the Raman laser.

The point source interferometry (PSI) is an ideal method to create spatial fringe in space.



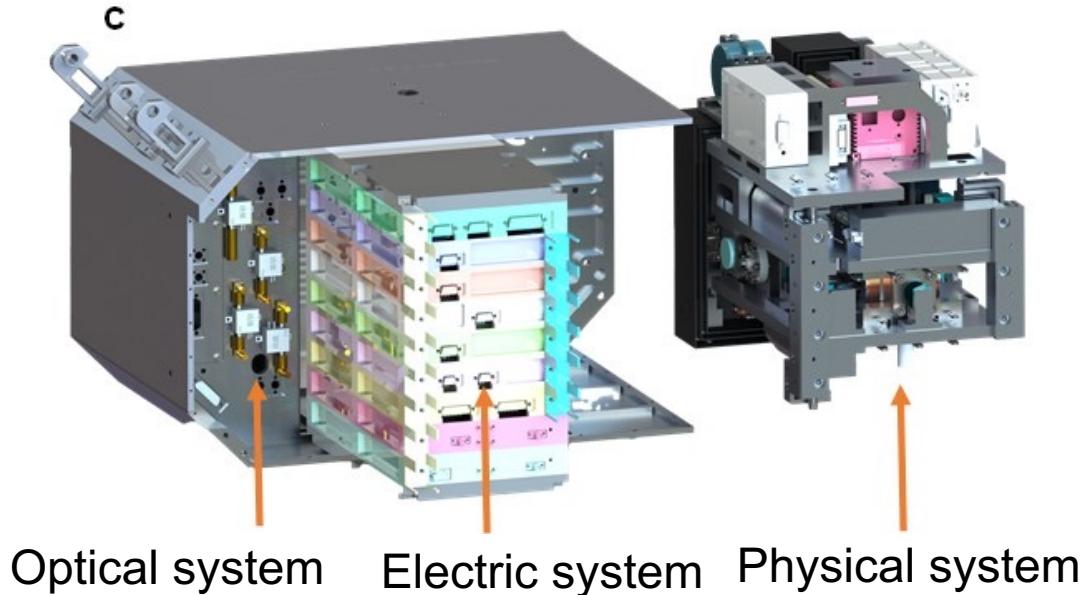
Susannah M. Dickerson, et al. PRL 111, 083001 (2013)

Gregory W. Hoth, et al. APL 109, 071113 (2016)

Special design:
The direction of the Raman laser is consistent with the direction of imaging to avoid reducing the fringe's contrast

Design of the payload

System configuration



Optical system Electric system Physical system

Physical system: $31\text{ cm} \times 20\text{cm} \times 25\text{ cm}$

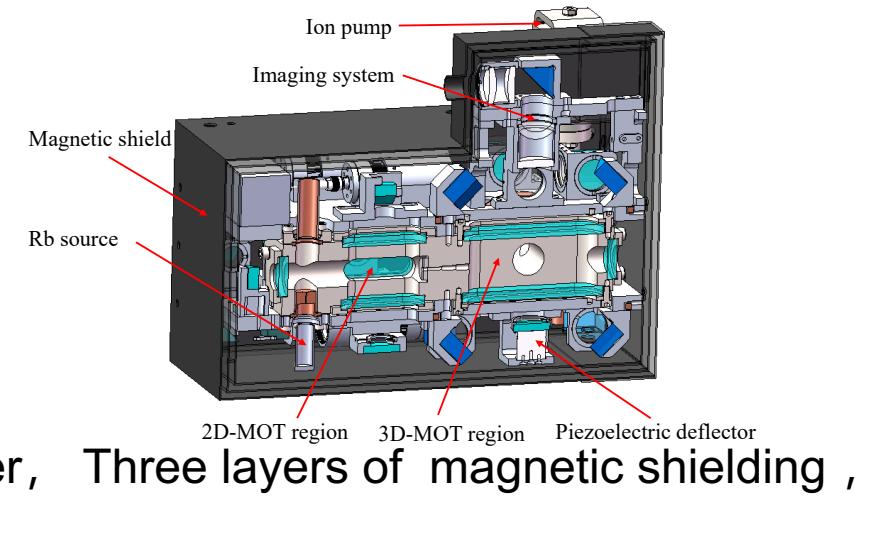
Optical system: $24\text{ cm} \times 10\text{cm} \times 25\text{ cm}$

electric system: $24\text{ cm} \times 14\text{cm} \times 25\text{ cm}$

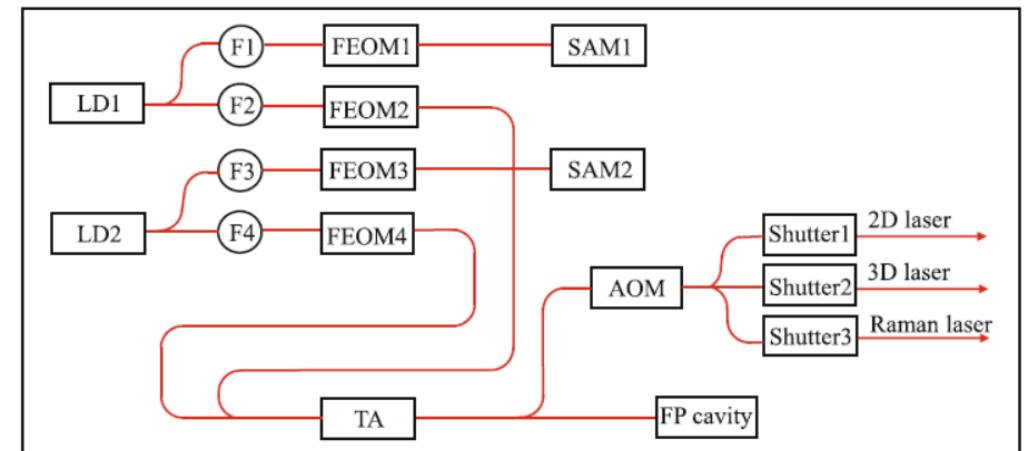
Total: $33\text{ cm} \times 46\text{ cm} \times 26\text{ cm}$

Weight: 37 kg

Physical system



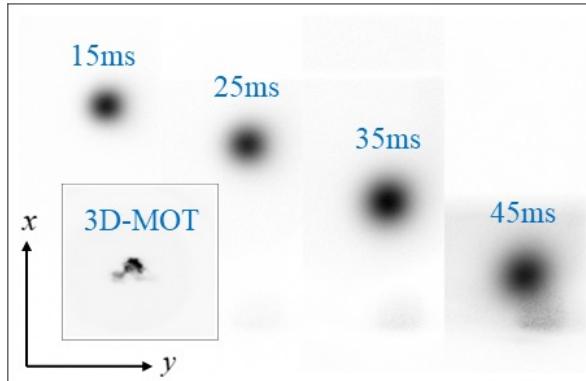
Optical system



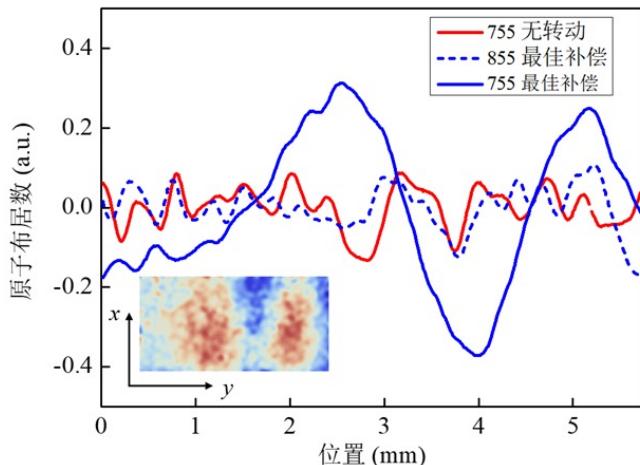
Sideband frequency stabilization, sidebands modulation,
Fused silica optical bench

Ground test

Function test



Cold atom preparing: 10^8 , 5 μK



Atom interference : 5 ms

M. He, et al. npj Microgravity 9, 58 2023

Environmental test



Thermal Cycle



Vibration test

Other tests

- ◆ electromagnetic compatibility
- ◆ Medical Science
- ◆ Ergonomics

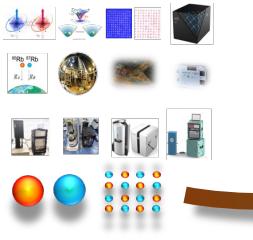
Launch and install



Launched by Tianzhou-5 cargo spacecraft (2022/9)



The Space AI in the HMLR (2022/12)

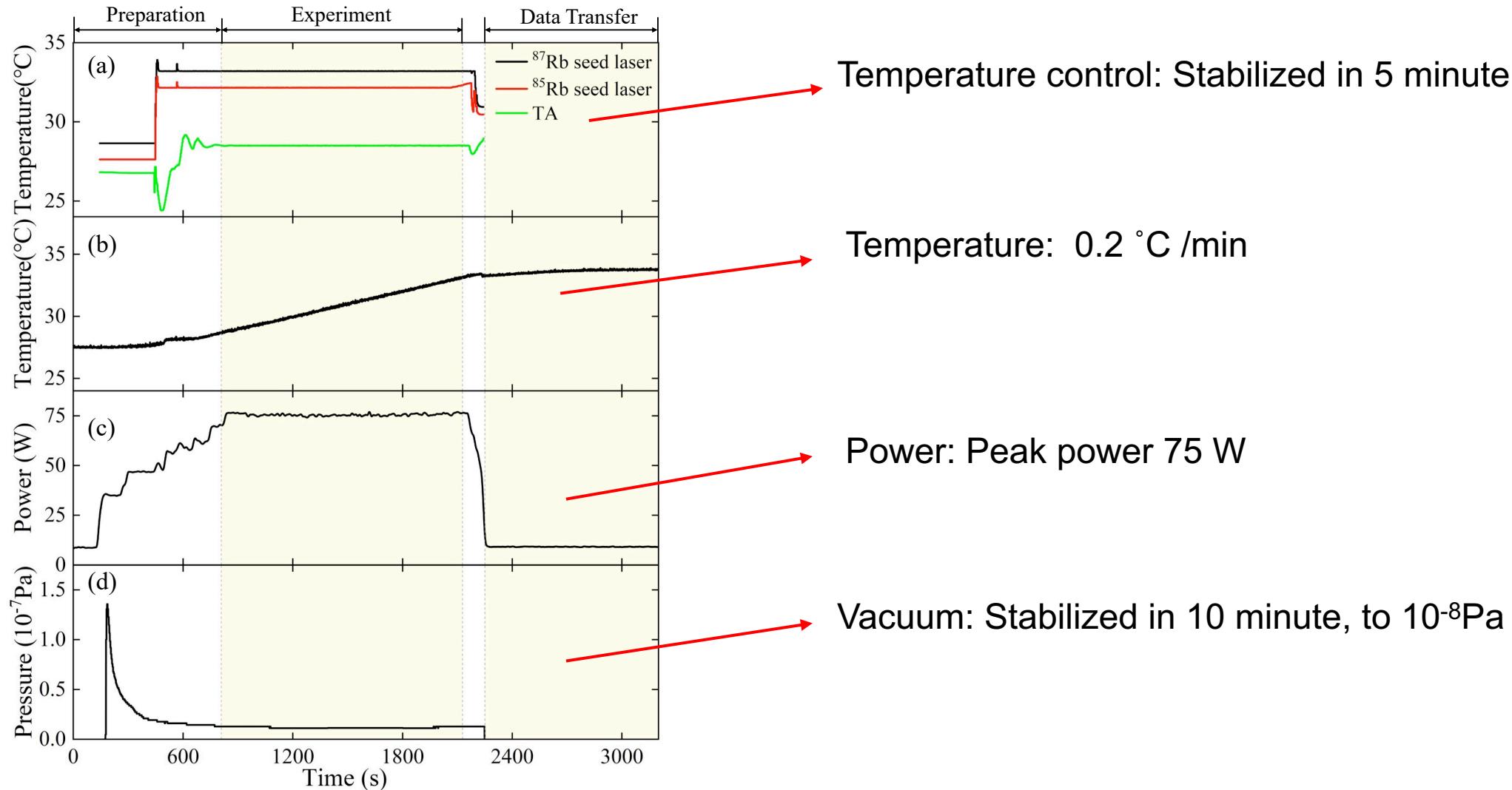


OUTLINE

- Why AI in space
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- CSS-AI: experiments

In orbit test

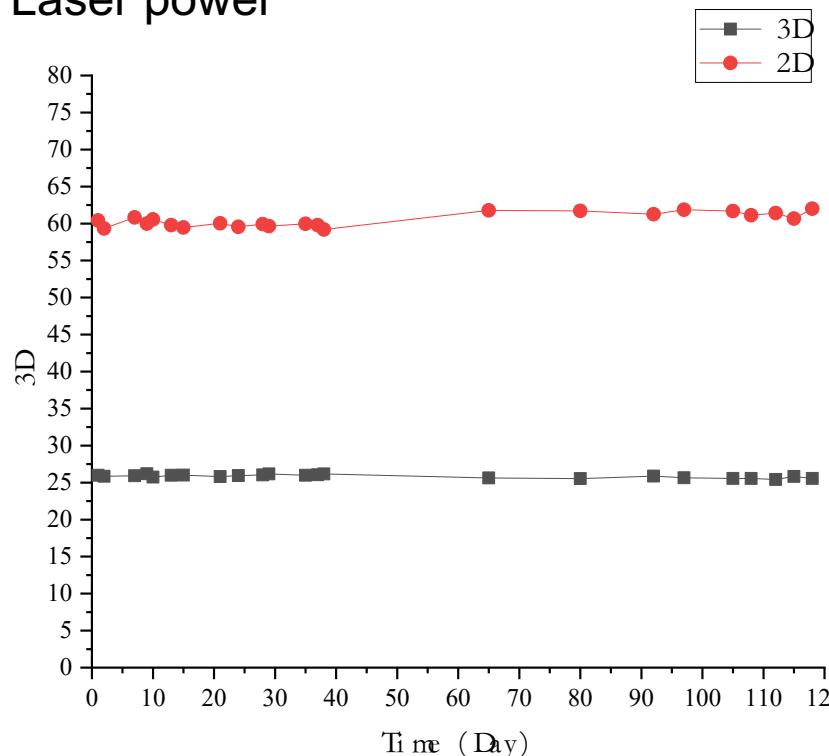
Intermittent operation mode, each experiment lasts for 50-70 min



In orbit test

Laser power stability

In orbit monitor the power of the 2D and 3D
Laser power



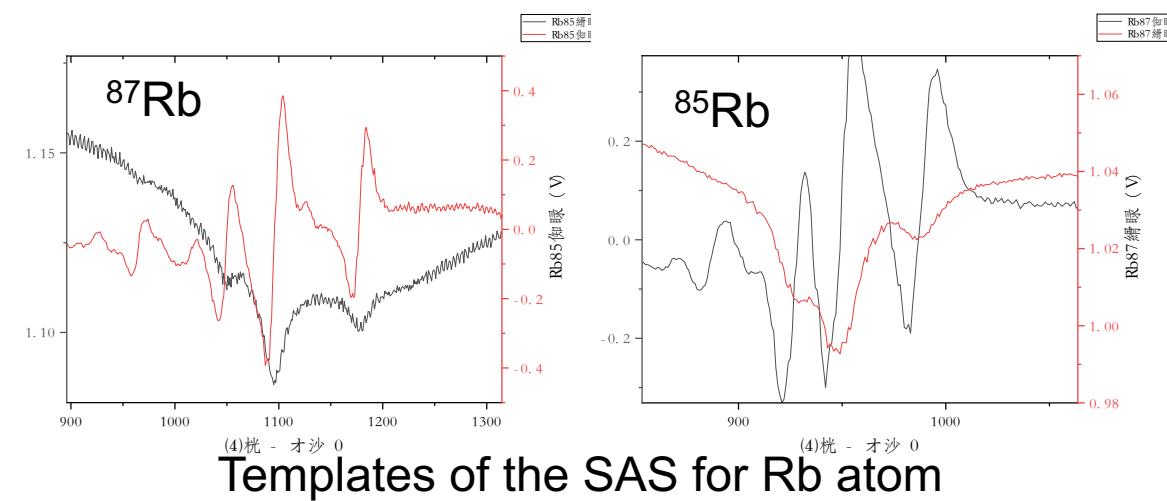
Fluctuation: <1.5% for more than 100 days

Laser frequency locking

In orbit realization of the auto frequency lock of the two
seed lasers

$$\text{Corr}(m) = \sum_n \frac{x(n)y(n-m)}{\sqrt{\sum_k x^2(k) \sum_k y^2(k)}}$$

Qi-Xue Li, et al. Optics and Lasers in Engineering 126 (2020) 105881

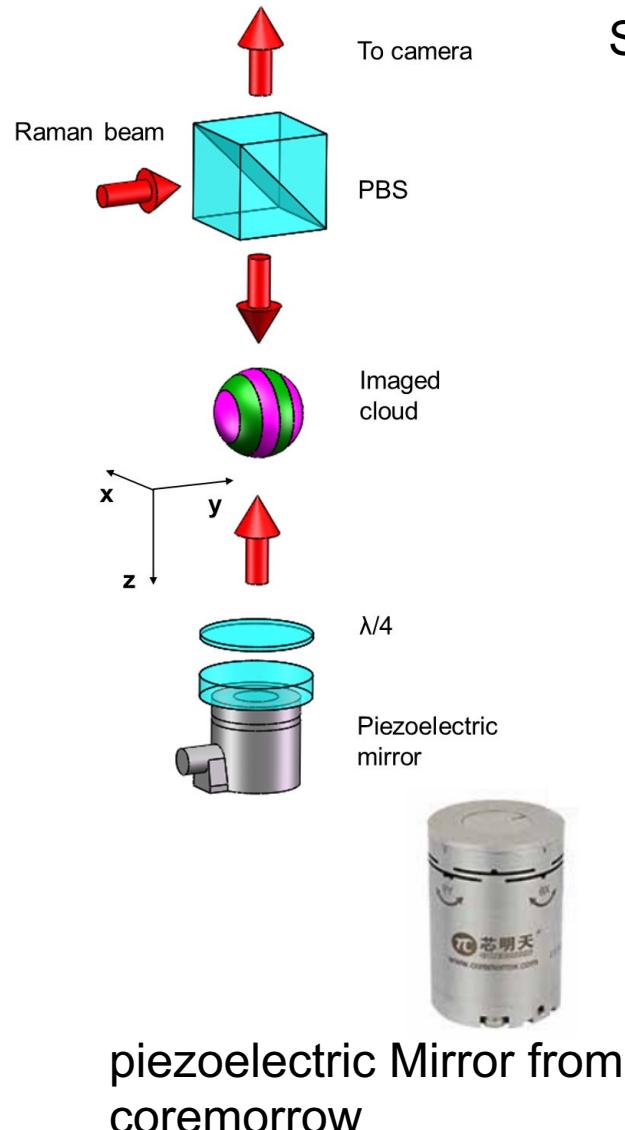


Templates of the SAS for Rb atom

success rate : 100% for Rb^{85} 95% for Rb^{87}
Frequency fluctuation after locking

0.94 MHz for Rb^{85} 0.80 MHz for ^{87}Rb

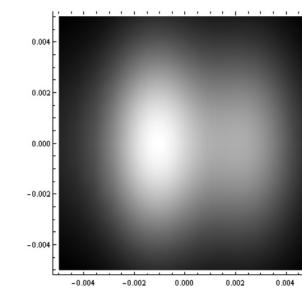
Interference phase of the PSI



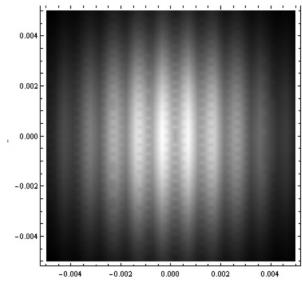
Spatial phase of PSI without rotation the angle of the Raman laser

$$\phi = k_{eff} a_z T^2 + \sum_i k_{eff} 2\Omega_i v_j T^2 \quad i = (x, y), j = (y, x)$$

Problem: For a fix rotation rate (~ 1 mrad/s for the CSS) the spatial frequency is related to the interference time



Frequency too low



Frequency too high

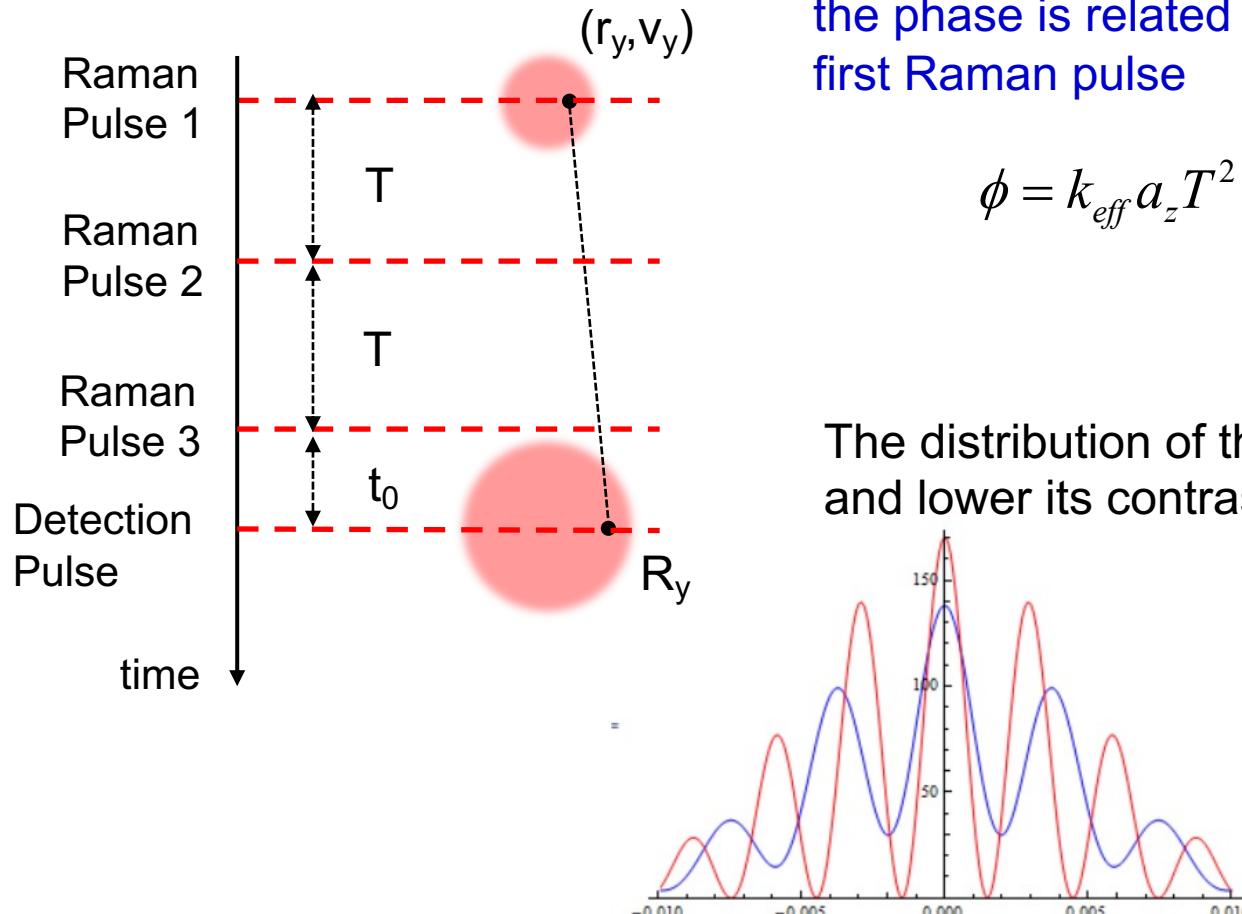
Introduce a Piezoelectric mirror, the phase of the Spatial fringe is

$$\phi = k_{eff} a_z T^2 + \sum_i k_{eff} [2\Omega_i v_j T^2 + \theta_{i,1} r_j + \theta_{i,3} (r_j + 2v_j T)]$$

Can adjust the spatial frequency and its direction

piezoelectric Mirror from
coremorrow

Optimizing the Raman laser's angle



Problem: what we measured is the position of atom at the detection time, but the phase is related to the position and velocity of atom at the time of the first Raman pulse

$$\phi = k_{eff} a_z T^2 + \sum_i k_{eff} [2\Omega_i v_j T^2 + \theta_{i,1} r_j + \theta_{i,3} (r_j + 2v_j T)]$$
$$R_j = r_j + v_j (2T + t_0)$$

The distribution of the atom will influence the spatial frequency of the fringe and lower its contrast.

$$\theta_{j,1} = \frac{-t_0 \theta_{j,3} + 2 \Omega_j T^2}{2 T + t_0} \quad (1)$$

$$\phi_o = k_{eff} a_z T^2 + \sum_{i=x,y} f_i R_i,$$
$$f_{i0} = \frac{2k_{eff}}{2T+t_0} (\theta_{j,3} T + \Omega_j T^2),$$

Blue: rotation with a fix rate $\theta_{i,3} = -\theta_{i,1}$
Red: rotation according to Eq. (1)

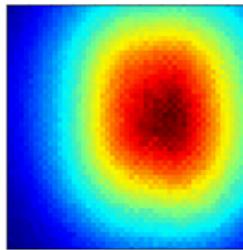
Eliminate the offset and distributions of the position and velocity of the atom cloud and maximize the fringe's contrast.

Extracting the spatial fringe from the background

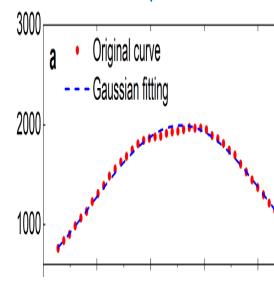
Problem: the contrast of the fringe is low, and the expression of the envelop is unknown.

Design a scheme to extract the fringe

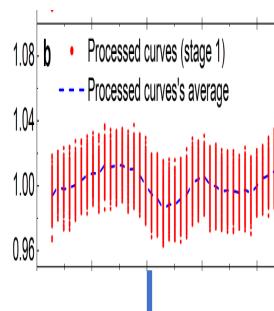
1.Origin
PSI image



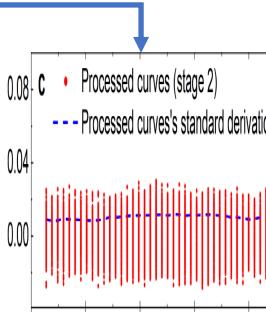
2.Averaged
to 1D



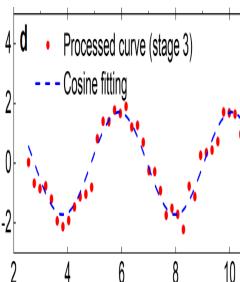
3.Divided by
Gaussian fitting



4.divided by
the curves'
average



5.divided by
the curves'
standard
derivation



Check this scheme by numeral simulation

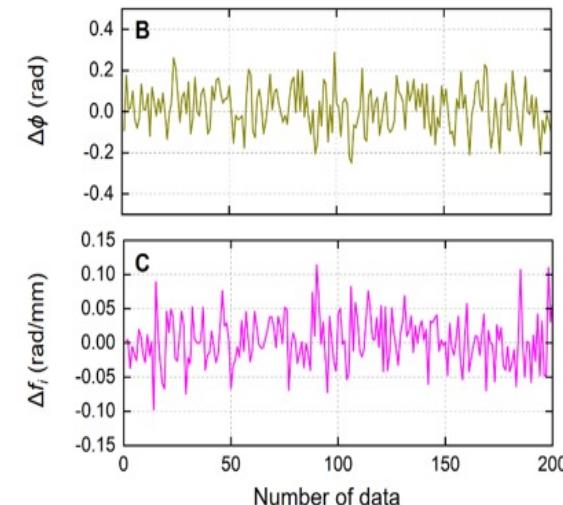
$$R_j = amp_{noise} + f(x)A \cdot \text{Exp}[(-x - x_0)^2 / \sigma x^2] * (1 + g(x)C \cdot \text{Cos}[\omega(x - x_0) + pha_{noise}])$$

f(x) represents the offset and g(x) represents the amplitude

set value VS fitted value

phase difference:
 $\Delta\phi = 16 \pm 109$ mrad

spatial frequency
difference: $\Delta f = 3 \pm 38$
mrad/mm.



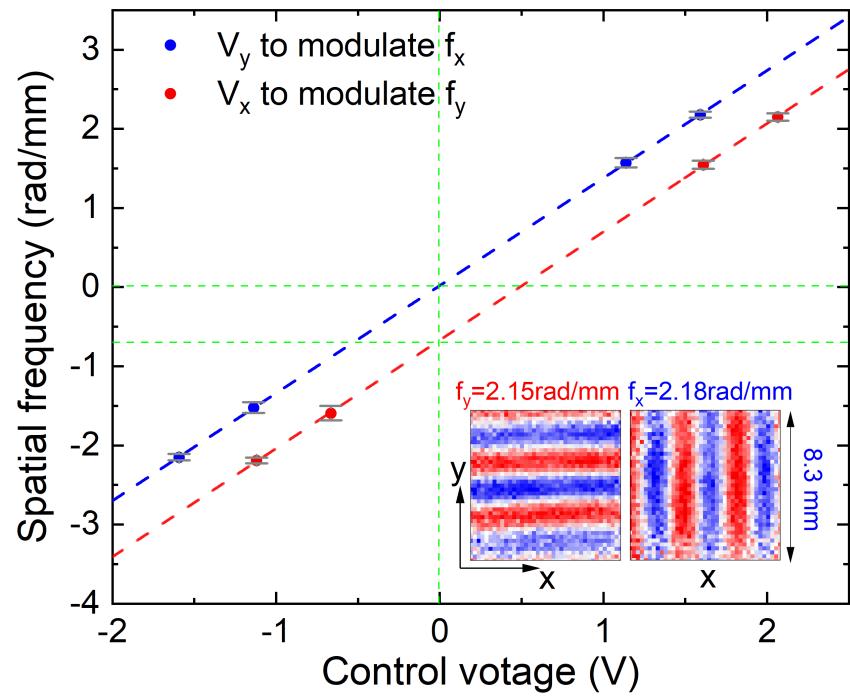
The method has no bias and near optimal

Calibration the angle of the Raman laser in orbit

Problem: The rotation is extract from the PSI fringe's spatial frequency, the spatial frequency is closely relative to angle of the mirror

$$f_i = \frac{2k_{eff}}{2T + t_0} (\theta_{j,3}T + \Omega_j T^2)$$

How to calibrate the angle of the mirror in orbit?



By changing the rotation angle and measure the spatial frequency, one can separate the rotation angle (slope) and the rotation rate (offset).

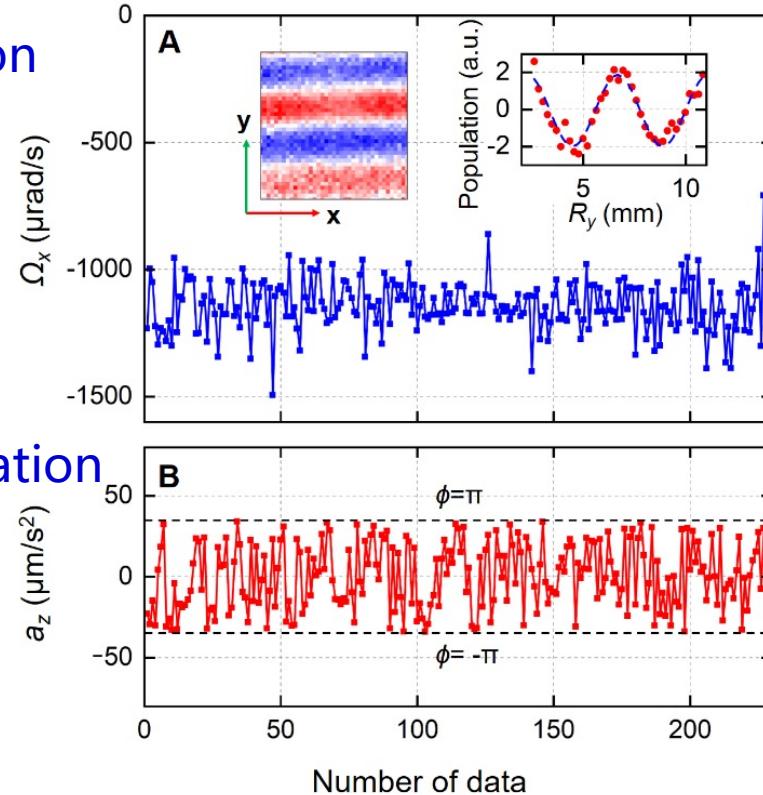
$$\alpha_x = 116.75 \pm 0.41 \mu\text{rad/V}$$
$$\alpha_y = 115.21 \pm 0.20 \mu\text{rad/V}.$$

$$\Omega_x = (-115.3 \pm 1.2) \times 10^{-5} \text{ rad/s},$$
$$\Omega_y = (-0.37 \pm 0.57) \times 10^{-5} \text{ rad/s}.$$

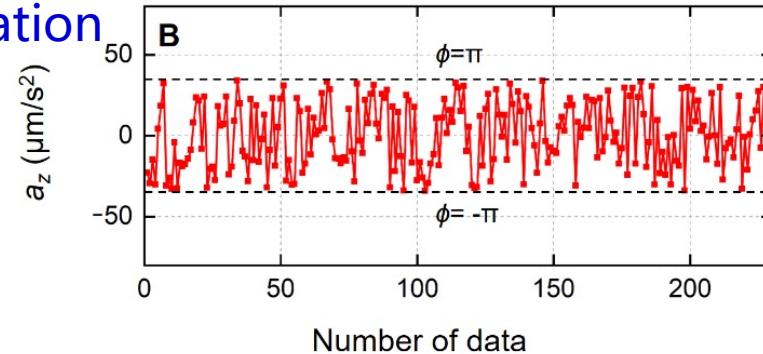
Rotation and acceleration measurement

Rotation and acceleration measurement with $T=75$ ms

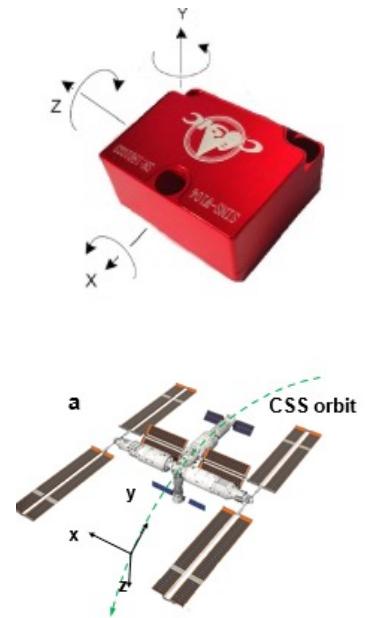
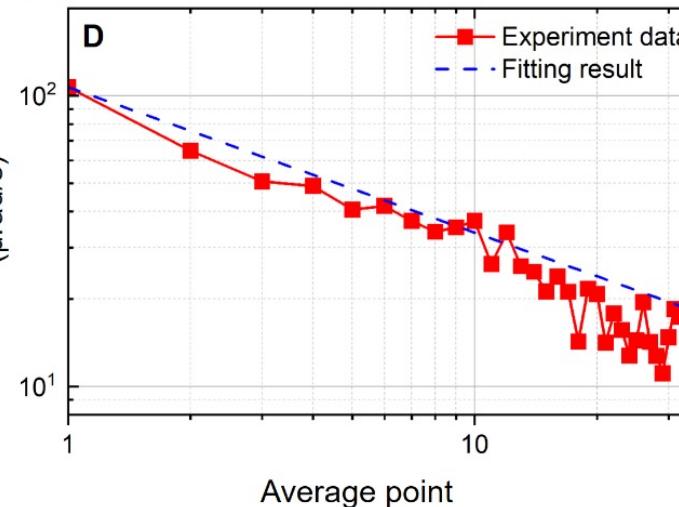
Rotation



Acceleration



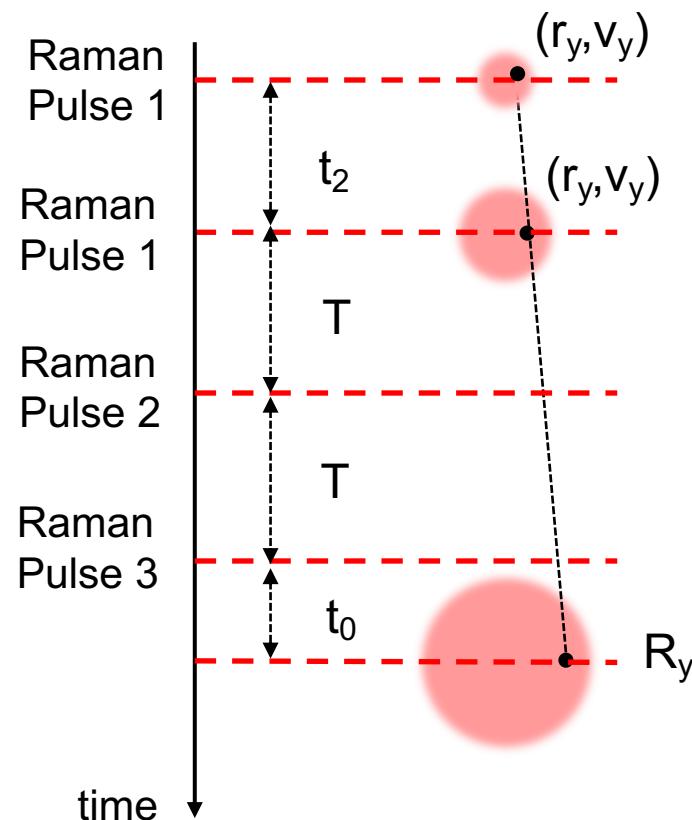
Allan deviation of Ω_x
($\mu\text{rad/s}$)



Resolution for rotation: 1.7×10^{-5} rad/s for 32 PSI measurements

Resolution for acceleration: 1.0×10^{-6} m/s² for one PSI measurement

Systemic effect estimation



Exact formulars of the phase and spatial frequency of PSI

$$\begin{cases} \phi = k_{eff} a_z T^2 + \sum_i k_{eff} [2\Omega_i v_j T^2 + \theta_{i,1} r_j + \theta_{i,3} (r_j + 2v_j T)] \\ R_j = r_j + v_j (2T + t_0) \end{cases}$$

↓ Integrated over the atom cloud's distributions

$$\phi_I = \phi_o$$

$$+ k_{eff} \sum_i \delta_i \left(\frac{t_0}{t} + \frac{t - t_0}{t} \frac{\sigma_{\rho i}^2}{\sigma_{vi}^2 t^2 + \sigma_{\rho i}^2} \right) R_i \Delta \theta_j$$

$$+ k_{eff} \sum_i \delta_i \frac{t - t_0}{t} \cdot \frac{\sigma_{vi}^2 t^2 \rho_{i0} - \sigma_{\rho i}^2 v_{i0} t}{\sigma_{vi}^2 t^2 + \sigma_{\rho i}^2} \Delta \theta_j$$

$$f_i = f_{io} + \Delta f_i$$

$$f_i + k_{eff} \left(\frac{t_0}{t} + \frac{t - t_0}{t} \frac{\sigma_{\rho i}^2}{\sigma_{vi}^2 t^2 + \sigma_{\rho i}^2} \right) \Delta \theta_j \cdot$$

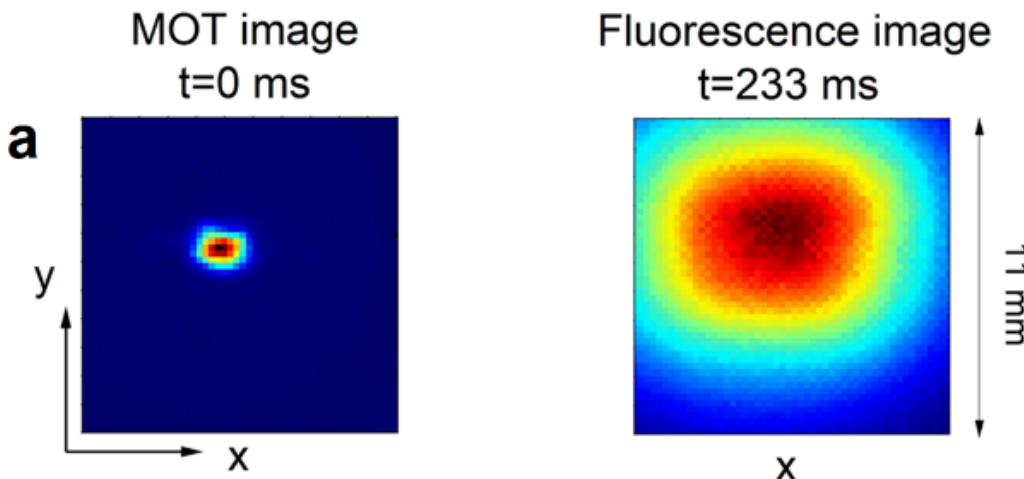
Acceleration and rotation can be accuracy extracted through the above two equations.

Systemic effect estimation

One should measure or estimate all parameters and their uncertainty to estimate the value of rotation.

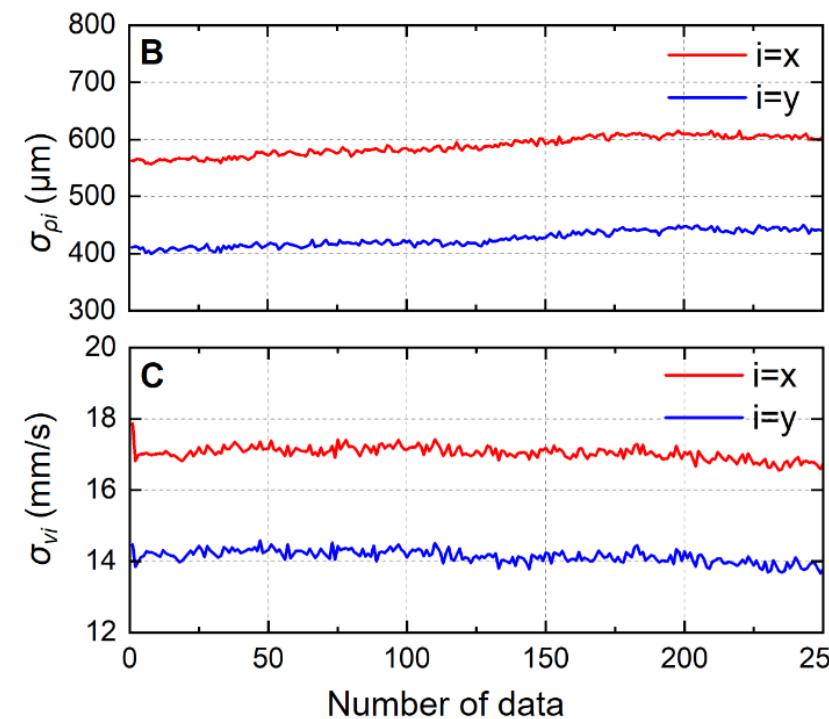
One example: velocity and position distributions of the atom cloud.

$$F(\rho_i, v_i) = N_1 e^{-\frac{(\rho_i - \rho_{i0})^2}{2\sigma_{\rho i}^2}} e^{-\frac{(v_i - v_{i0})^2}{2\sigma_{v i}^2}}$$



Position and velocity distributions are measured by the TOF method.

$$\begin{aligned} T_x &= 2.94 \pm 0.06 \text{ } \mu\text{K} \\ T_y &= 2.02 \pm 0.05 \text{ } \mu\text{K} \end{aligned}$$



Position distribution

x: 0.590 mm
y: 0.427 mm

Velocity distribution

x: 17.04 mm/s
y: 14.13 mm/s

Systemic effect estimation

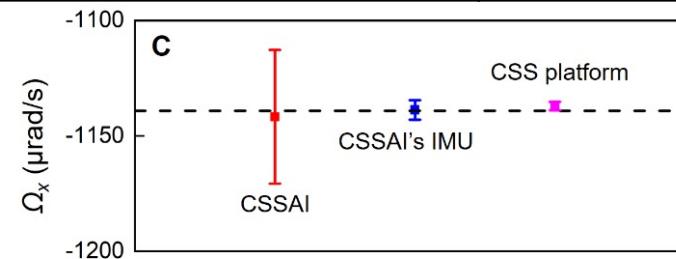
Rotation measurement error estimation

Parameters terms	Parameters values	Evaluated result ($\mu\text{rad/s}$)
Spatial frequency (fitting result) (rad/mm)	$f_y=1.497\pm0.013$	-1142 ± 17
magnification factor of the imaging system (a.u.)	2.22 ± 0.03	±21
Angles of 3 rd Raman laser pulses (μrad)	$\theta_{x,3}=202.94\pm0.72$	±10
Difference angle of $\theta_{x,1}$ (rad)	$\Delta\theta_x=2.41\pm0.41$	±1
Interference time (μs)	$T=75137.3\pm0.23$	$\pm3\times10^{-3}$
Time before the 1 st Raman pulse (μs)	$t_0=43245.8\pm0.13$	$\pm2\times10^{-5}$
Time after the 3 rd Raman laser pulse (μs)	$t_1=40146\pm10$	$\pm9\times10^{-2}$
Width of the Raman π pulse (μs)	$\tau=17\pm(5\times10^{-5})$	$\pm6\times10^{-7}$
Effective wave vector (m^{-1})	$k_{\text{eff}}=16105813.75\pm0.09$	$\pm9\times10^{-6}$
Width of the MOT's position (mm)	$\sigma_{\text{pi}}=0.427\pm0.013$	$\pm3\times10^{-2}$
Width of the MOT's velocity (mm/s)	$\sigma_{\text{vi}}=14.13\pm0.18$	$\pm1\times10^{-2}$
Magnetic field	$B_0=504.7\pm1.3 \text{ mG}$ $\gamma_{i,2}=\pm1.3 \text{ G/m}^2$	$\pm2\times10^{-1}$
In total		-1142 ± 29

CSSAI $(-114.2\pm2.9)\times10^{-5} \text{ rad/s}$

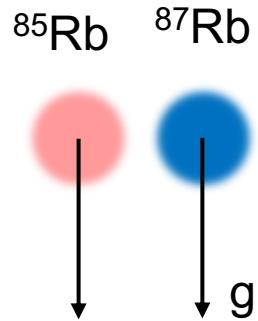
CSSAI's IMU $(-113.87\pm0.41)\times10^{-5} \text{ rad/s}$

CSS platform $(-113.70\pm0.18)\times10^{-5} \text{ rad/s}$



What we can do next

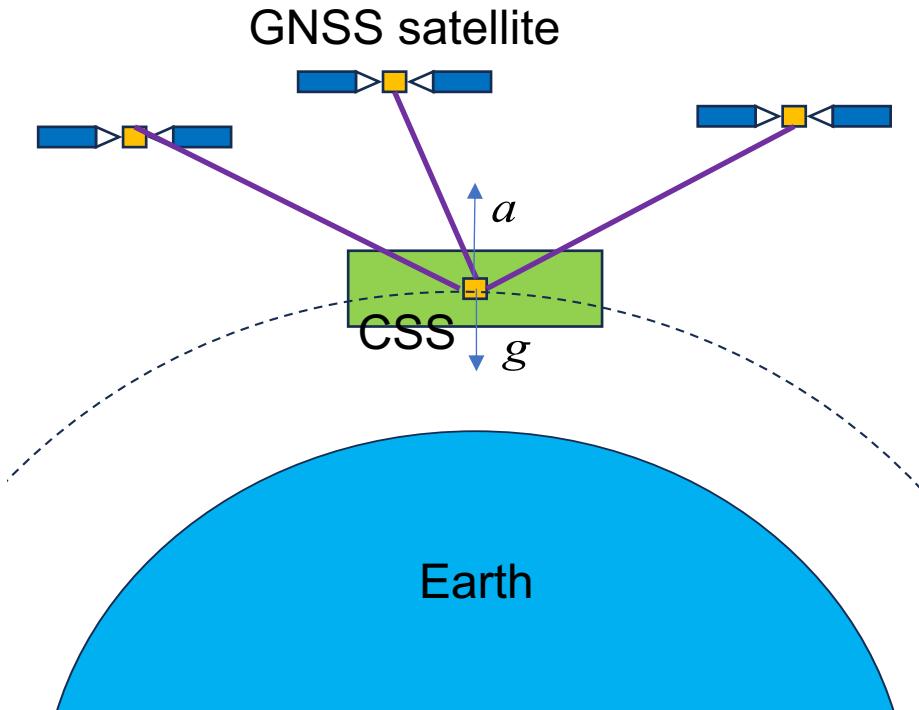
EP test



$$\eta = \frac{\Delta\phi}{k_{eff}gT^2}$$

$\sim 10^{-9}$

Gravity field mapping



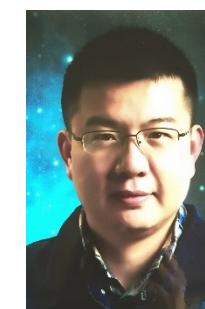
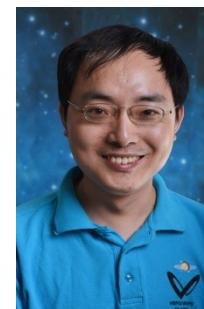
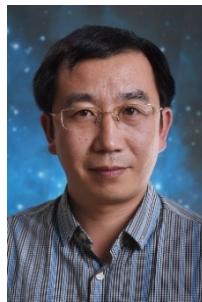
$$g = a_{\text{Residual}} + a_{\text{Motion}}$$

$\sim 10^{-6}$ g

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<http://cap.apm.ac.cn/>

ZMS - AMP



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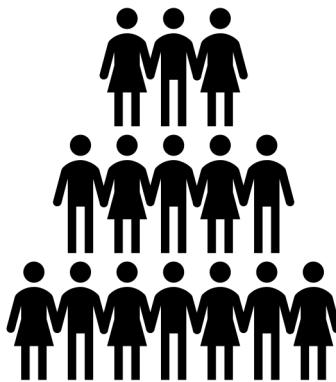
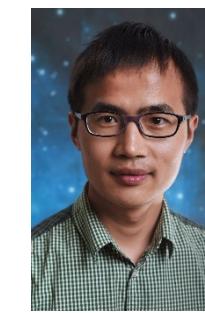
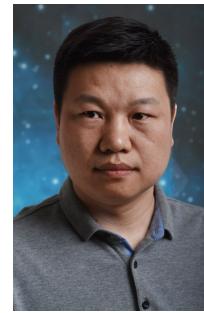
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All of you,
for your attention!